

EZM-9950 96 x 96 1/4 DIN Universal Input Programmable Timer & Counter with Output Module System

- 6 digits Process (PV) and 6 digits Set (SV) Value Display
- Operation with 2 Set Value
- Reset , Pause and ChA-ChB Counting Inputs
- Configurable Counter / "Totalizer Counter", Batch Counter, Timer, Chronometer, Frequencymeter and Tachometer Functions
- Programmable Time Bases for Timer and Chronometer (Second , Minute , Hour)
- Operation with Automatic and Manual Reset
- Output Module System
- NPN/PNP Type Operation
- INC, DEC, INC / INC, INC / DEC, UP / DOWN, x1/x2/x4 Counting with Phase Shifting Property in Counter Function
- Multiplication Coefficient and Decimal Point Position
- Different Alarm Alternatives in Frequencymeter and Cycle Measuring Functions
- Absolute or Offset Operation in Counter Function
- RS-232 (standard) or RS-485 (optional) Serial Communication with Modbus ASCII or RTU Protocol

ABOUT INSTRUCTION MANUAL

Instruction manual of EZM-9950 Programmable Timer&Counter consists of two main sections. Explanation of these sections are below. Also, there are other sections which include order information and technical specifications of the device. All titles and page numbers in instruction manual are in "CONTENTS" section. User can reach to any title with section number.

Installation:

In this section, physical dimensions of the device, panel mounting, electrical wiring, module mounting in the device, physical and electrical installation of the device to the system are explained.

Operation and Parameters:

In this section, user interface of the device, how to access to the parameters, description of parameters are explained.

Also in these sections, there are warnings to prevent serious injury while doing the physical and electrical mounting or using the device.

Explanation of the symbols which are used in these sections are given below.



This symbol is used for safety warnings. User must pay attention to these warnings.



This symbol is used to determine the dangerous situations as a result of an electric shock. User must pay attention to these warnings definitely.



This symbol is used to determine the important notes about functions and usage of the device

CONTENTS
1.PREFACEPage 6
1.1 GENERAL SPECIFICATIONS
1.2 ORDERING INFORMATION
1.3 WARRANTY 1.4 MAINTENANCE
2.INSTALLATIONPage 9
2.1 GENERAL DESCRIPTION
2.2 DIMENSIONS 2.3 PANEL CUT-OUT
2.4 ENVIRONMENTAL RATINGS
2.5 PANEL MOUNTING
2.6 INSTALLATION FIXING CLAMP
2.7 REMOVING FROM THE PANEL
2.8 SELECTION OF OPERATION FUNCTION AND INPUT TYPE WITH DIP SWITCH
SWITCH
3.ELECTRICAL WIRINGSPage 15
3.1 TERMINAL LAYOUT AND CONNECTION INSTRUCTION
3.2 ELECTRICAL WIRING DIAGRAM
3.3 CONNECTION OF DEVICE SUPPLY VOLTAGE INPUT 3.4 COUNTING INPUT CONNECTION
3.4.1 PROXIMITY & SWITCH CONNECTION
3.4.2 INCREMENTAL ENCODER & SWITCH CONNECTION
3.4.3 SWITCH CONNECTION
O F OALL VANIO 1001 ATION TEOT VALUED OF EZM 0050 PROOPAMMARI F
3.5 GALVANIC ISOLATION TEST VALUES OF EZM-9950 PROGRAMMABLE TIMER&COUNTER AND OUTPUT MODULES
TIMENACOUNTENAND OUTFUT MODULES
4.DEFINITIONS AND SPECIFICATIONS OF OUTPUT MODULES Page 22
4.1 EMO-900 RELAY OUTPUT MODULE
4.2 EMO-910 SSR DRIVER MODULE
4.3 EMO-920 DIGITAL (TRANSISTOR) OUTPUT MODULE 4.4 INSTALLING AND PULLING OUT OUTPUT MODULES
4.5 TO STICK OUTPUT MODULES' LABELS TO THE DEVICE
5.CONNECTION TERMINALS OF OUTPUT MODULES AND CONNECTION WIRINGPage 27
5.1 EMO-900 RELAY OUTPUT MODULE CONNECTION
5.2 EMO-910 SSR DRIVER MODULE CONNECTION
5.3 EMO-920 DIGITAL (TRANSISTOR) OUTPUT MODULE CONNECTION
6.CONNECTIONS FOR RS-232 / RS-485 SERIAL COMMUNICATIONPage 29
6.1 CABLE CONNECTION BETWEEN RS-232 TERMINAL OF THE DEVICE
AND PC
6.2 CONNECTION FOR RS-485 SERIAL COMMUNICATION
6.3 INSTALLING RS-232 / RS-485 SERIAL COMMUNICATION MODULES TO
THE DEVICE
7.DEFINITION OF FRONT PANEL AND ACCESSING TO THE SET
PARAMETERSPage 33
7.1 DEFINITION OF FRONT PANEL 7.2 POWER ON OBSERVATION OF EZM - 9950 PROGRAMMABLE TIMER &
COUNTER AND SOFTWARE REVISION ON THE DISPLAY
COUNTELLAND COLLINAISE ISENION ON THE DISPERI

7.3 ADJUSTMENT OF SET1 AND SET2 VALUES 7.4 RESETTING COUNT VALUE AND OBSERVING TOTAL COUNT VALUE IN COUNTER / "TOTALIZER COUNTER" FUNCTION
7.5 COUNTER / "TOTALIZER COUNTER" PARAMETERS 7.5.1 COUNTER / "TOTALIZER COUNTER" APPLICATIONS EXAMPLES
7.6 BATCH COUNTER PARAMETERS 7.6.1 BATCH COUNTER APPLICATIONS EXAMPLES
7.7 TIME RELAY PARAMETERS 7.7.1 TIMER APPLICATIONS EXAMPLES
7.8 FREQUENCYMETER / TACHOMETER PARAMETERS 7.8.1 FREQUENCYMETER / TACHOMETER APPLICATIONS EXAMPLES
7.9 CHRONOMETER PARAMETERS 7.9.1 CHRONOMETER APPLICATIONS EXAMPLES
7.10 ACCESSING TO THE PROGRAM PARAMETERS
8.PROGRAM PARAMETERSPage 68
9.FAILURE MESSAGES IN EZM-9950 PROGRAMMABLE TIMER & COUNTER Page 101
10.SPECIFICATIONSPage 103

EU DECLARATION OF CONFORMITY

Manufacturer Company Name : Emko Elektronik A.S.

Manufacturer Company Address: DOSAB, Karanfil Sokak, No:6, 16369 Bursa, Turkiye

The manufacturer hereby declares that the product conforms to the following standards and conditions.

Product Name : Programmable Timer & Counter

Model Number : EZM-9950

Type Number : EZM-9950

Product Category laboratory use : Electrical equipment for measurement, control and

Conforms to the following directives :

73 / 23 / EEC The Low Voltage Directive as amended by 93 / 68 / EEC

89 / 336 / EEC The Electromagnetic Compatibility Directive

Has been designed and manufactured according to the following specifications

EN 61000-6-4:2001 EMC Generic Emission Standard for the Industrial Environment

EN 61000-6-2:2001 EMC Generic Immunity Standard for the Industrial Environment

EN 61010-1:2001 Safety Requirements for electrical equipment for measurement, control and laboratory use

1.Preface

EZM Series Programmable Timer & Counter can be used in package machines, production and quality control rollers, in cutting and processing machine of glass, plastic, marble, sheet, iron, fabric all measuring and controlling of dimension, count, total count, speed, cycle, productivity, time and can be adapted easily to all mechanical construction and automation system. They can be used in many application with their control outputs, serial communication unit and output modules.

Some application fields which they are used are below:

Application Fields

Glass

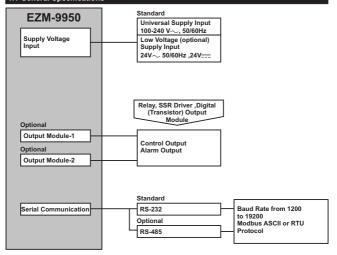
Plastic

Marble Sheet iron

Automative

Machine production industries

1.1 General Specifications



1.2 Ordering Information

II Function of Device

EZ	M-9950 (98x96 1/4 DIN)					
Α	Supply Voltage 100-240V~ (-15%;+10%) 50/60Hz					
1						
2	24 V~ (-15%;+10%) 50/60Hz 24V===(-15%;+10%)					
9	Customer (Maximum 240V~ (-15%;+10%))50/60Hz					

D	Serial Communication	Product Code
0	None	-
1	RS-232	EMC-900
2	RS-485	EMC-910

		Product Code
00	None	-
01	Relay Output Module(5A@250V~Resistive Load)	EMO-900
		EMO-910
03	Digital(Transistor) Output Module	EMO-920

		Frounct Code
	None	-
01	Relay Output Module(5A@250V~Resistive Load)	EMO-900
		EMO-910
03	Digital(Transistor) Output Module	EMO-920

	0	Counter / "Totalizer Counter"
1	1	Batch Counter
2 Timer		Timer
1	3	Frequencymeter and Tachometer
	4	Chronometer

ı	V	Input Type
	0	NPN
	1	PNP

All order information of EZM-9950 Programmable Timer&Counter are given on the table at left. User may form appropriate device configuration from information and codes that at the table and convert it to the ordering codes.

Firstly, supply voltage then output modules and other specifications must be determined. Please fill the order code blanks according to your needs.

Please contact us, if your needs are out of the standards.



≂Symbol means Vac and Vdc

1.3 Warranty

EMKO Elektronik warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date. This warranty is in force if duty and responsibilities which are determined in warranty document and instruction manual performs by the customer completely.

1.4 Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts.

Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.), Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

2.Installation



Before beginning installation of this product, please read the instruction manual and warnings below carefully.

In package.

- One piece unit
- Two pieces mounting clamps
- -One piece instruction manual

A visual inspection of this product for possible damage occured during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and separate the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

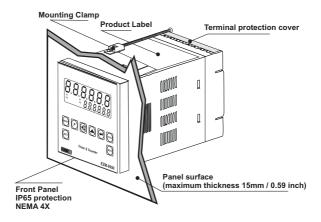
Do not use the unit in combustible or explosive gaseous atmospheres.

During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

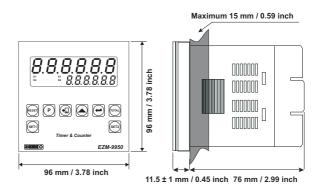
Montage of the product on a system must be done with it's fixing clamps. Do not do the montage of the device with inappropriate fixing clamp. Be sure that device will not fall while doing the montage.

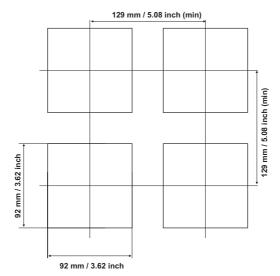
It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

2.1 General Description



2.2 Dimensions





2.4 Environmental Ratings

Operating Conditions



Operating Temperature : 0 to 50 °C



Max. Operating Humidity: 90% Rh (non-condensing)



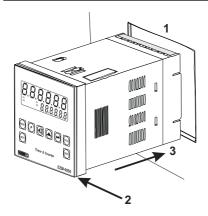
Altitude : Up to 2000m.



Forbidden Conditions: Corrosive atmosphere Explosive atmosphere

Home applications (The unit is only for industrial applications)

2.5 Panel Mounting

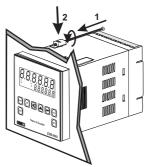


- 1-Before mounting the device in your panel, make sure that the cut-out is the right size.
- 2-Check front panel gasket position
- 3-Insert the device through the cut-out. If the mounting clamps are on the unit, put out them before inserting the unit to the panel.



During installation into a metal panel, care should be taken to avoid injury from metal burrs which might be present. The equipment can loosen from vibration and become dislodged if installation parts are not properly tightened. These precautions for the safety of the person who does the panel mounting.

2.6 Installation Fixing Clamp



The unit is designed for panel mounting.

- 1-Insert the unit in the panel cut-out from the front side.
- 2- Insert the mounting clamps to the holes that located top and bottom sides of device and screw up the fixing screws until the unit completely immobile within the panel

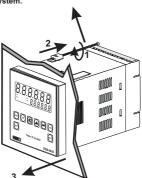


Montage of the unit to a system must be done with it's own fixing clamps. Do not do the montage of the device with inappropriate fixing clamps. Be sure that device will not fall while doing the montage.

2.7 Removing from the Panel



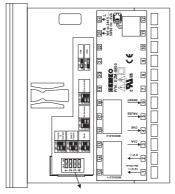
Before starting to remove the unit from panel, power off the unit and the related system.



- 1-Loosen the screws.
- 2-Pull mounting clamps from top and bottom fixing sockets.
- 3-Pull the unit through the front side of the panel

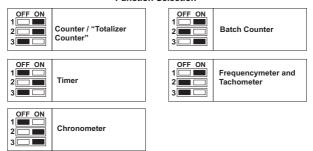


Operation function and input type (NPN / PNP) can be changed by DIP switch on the device.



DIP Switch is under cover and cover is on top side of the device

Function Selection



Input Type Selection

OFF ON	NPN		OFF ON 4	PNP
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3. Electrical Wirings



You must ensure that the device is correctly configured for your application. Incorrect configuration could result in damage to the process being controlled, and/or personal injury. It is your responsibility, as the installer, to ensure that the configuration is correct.

Parameters of the device has factory default values. These parameters must be set according to the system's needs.



Only qualified personnel and technicians should work on this equipment. This equipment contains internal circuits with voltage dangerous to human life. There is severe danger for human life in the case of unauthorized intervention.



Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.



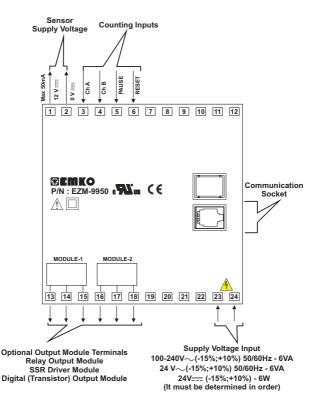
Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

3.1 Terminal Layout and Connection Instructions 6 mm/0.236 inch Wire Size: 1 2 3 4 5 6 7 8 9 10 11 12 24 screws terminal M3 Optional connections Empty terminals Torque 0.5 Nm Screw driver 0.8x3mm

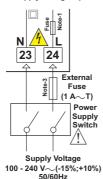
3.2 Electrical Wiring Diagram

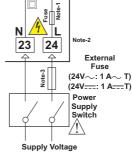


Electrical wiring of the device must be the same as 'Electrical Wiring Diagram' below to prevent damage to the process being controlled and personnel injury.



Connection of Universal Supply Voltage Input





24V~ (-15%;+10%) 50/60Hz or 24V== (-15%;+10%)

Note-1:

There is internal 33R Ω fusible flameproof resistor in 100-240 V \sim 50/60Hz

There is internal 4R7 Ω fusible flameproof resistor in 24V \sim 50/60Hz and 24V==

Note-2: "L" is "+", "N" is "-" for 24V=== supply voltage

Note-3: External fuse is recommended.



Make sure that the power supply voltage is the same indicated on the instrument.

Switch on the power supply only after that all the electrical connections have been completed.

Supply voltage range must be determined in order. While installing the unit, supply voltage range must be controlled and appropriate supply voltage must be applied to the unit. Controlling prevents damages in unit and system and possible accidents as a result of incorrect supply voltage.



There is no power supply switch on the device. So a power supply switch must be added to the supply voltage input. In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument. Power supply switch shall be easily accessible by the user.

Power switch must be two poled for seperating phase and neutral. On/Off condition of power switch is very important in electrical connection. On/Off condition of power switch must be signed for preventing the wrong connection.

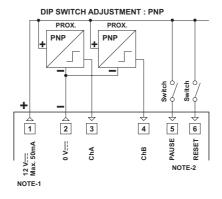
If an external fuse is used, it must be on phase connection in ~ supply input.

If an external fuse is used, it must be on (+) line connection in ==supply input.

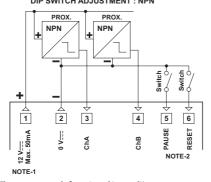


The instrument is protected with an internal fuse (Please refer to Note1 for information). In case of failure it is suggested to return the instrument to the manufacturer for repair.

3.4.1 Proximity & Switch Connection



DIP SWITCH ADJUSTMENT: NPN

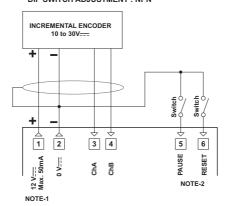


NOTE-1 : Auxiliary power supply for external transmitter $12V_{---} \pm 10\%$, 50 mA maximum with short circuit protection

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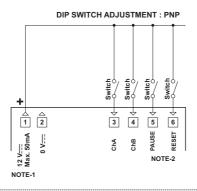
NOTE-1

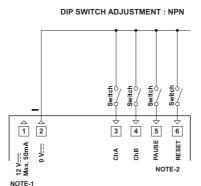
DIP SWITCH ADJUSTMENT: NPN



NOTE-1: Auxiliary power supply for external transmitter 12V== ±10%, 50 mA maximum short circuit protection

NOTE-2 : Reset and Pause inputs have protection time against electrical contact debounce. Protection time can be set with $\frac{P_{-0} - \frac{C}{2} \cdot H}{P_{-0} - \frac{C}{2} \cdot H}$ parameter. (2-250 msec.)

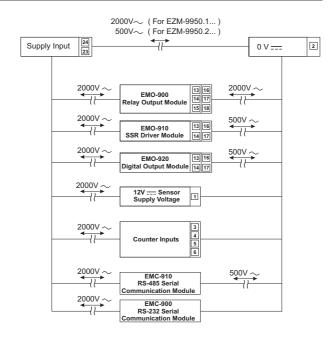




NOTE-1: Auxiliary power supply for external transmitter 12V=== ± 10%, 50 mA maximum short circuit protection

NOTE-2 : Reset and Pause inputs have protection time against electrical contact debounce. Protection time can be set with $[P_{-\Box} - \frac{1}{C} V]$ parameter. (2-250 msec.)

3.5 Galvanic Isolation Test Results of EZM-9950 Programmable Timer & Counter and Output Modules

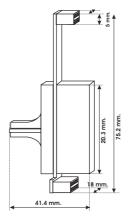


4. Definitions and Specifications of Output Modules

EZM-9950 programmable Timer &Counter is a modular product which is designed to operate with additional output units which user may need.

Two output modules can be plugged in the equipment by the user. User may configure the product for different applications according to the system requirements with the output modules which are described in this section.

Dimensions of Output Modules



4.1 EMO-900 Relay Output Module

EMO-900 Relay output module can be plugged in Module-1 or Module-2 socket to be used in applications that relay output is necessary

Specifications of EMO-900 Relay Output Module

Output : 5A @ 250V~, Single Open / Close Contact

Dimensions : 18x75.2x41.4mm

Electrical Life : 100.000 operation (Full Load)

Applications of EMO-900 Relay Output Module

It can be used for programmable different alarm functions as control or alarm output.

4.2 EMO-910 SSR Driver Module

EMO-910 SSR Driver Module can be plugged in Module-1 or Module-2 socket to be used in applications that SSR driver output is necessary

Specification of EMO-910 SSR Driver Module

: Maximum 20 mA, 15-18V === ±10%, isolated

Dimensions: 18x75.2x41.4mm

Applications of EMO-910 SSR Driver Module

It can be used for programmable different alarm functions as control or alarm output.

Note 1: SSR Driver Module must be preferred instead of relay output module in applications with short output period because of limited life of their relay contact (number of open/close events).

4.3 EMO-920 Digital (Transistor) Output Module

EMO-920 Digital (Transistor) Output Module can be plugged in Module-1 or Module-2 socket to be used in applications that digital output is necessary

Specifications of EMO-920 Digital (Transistor) Output Module

: Maximum 40 mA, 15-18V === ±10%, isolated

Dimensions: 18x75.2x41.4mm

Applications of EMO-920 Digital (Transistor) Output Module

It can be used for programmable different alarm functions as control or alarm output.

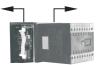
4.4 Installing and Pulling Out Output Modules



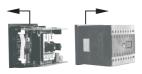
First, detach all cable connections from the device and uninstall it from the panel.



Suppress to the lock pins where top and bottom of the device



Pull the cover case with your other hand from front panel to rear



Pull out the cover case from the device



Slide output modules into socket.

Pull out the module from it's socket, instead of this module install the new one or other module user wants to use.



Replace the cover case by taking care of the terminal numbers should be at right position.

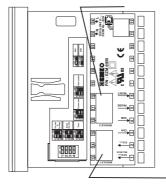


After adding or changing modules to the unit, these changes must be taken into consideration while mounting of the unit to the system. If mounting is incorrect, it can cause accidents to harm system, operator or person who does the mounting. Responsibility of these kind of harmful events belongs to the user.

4.5 To Stick Output Modules' Labels to the Equipment

Every module which is plugged in Module-1 or Module-2 socket has labels' for showing the relation between connection terminal and the device. These labels are attached to empty attachment places which are separated for Module-1 and Module-2 on the device. Labels for all modules and attachment places are shown below.

Label which is plugged in Module-2 socket, describes module termination connection is attached to this area.

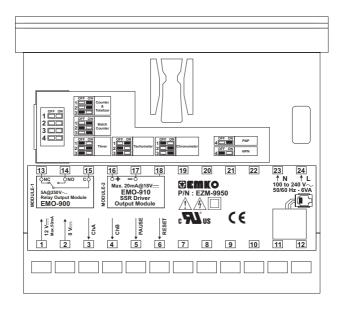


Label which is plugged in Module-1 socket, describes module termination connection is attached to this area.

LABELS FOR OUTPUT MODULES

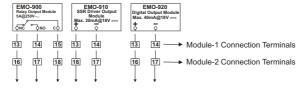


Example: If user installs EMO-900 Relay Output Module to Module-1 socket, EMO-910 SSR Output Module to Module-2 socket and attach the appropriate labels on the device view will be like below:

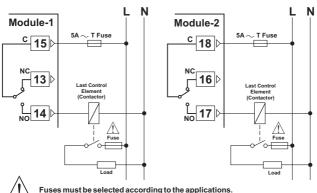


5. Connection Terminals of Output Modules and Connection Wirings

Module-1 / Module-2 Optional Output Modules

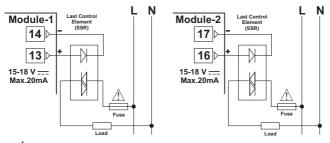


5.1 EMO-900 Relay Output Module Connection



Fuses must be selected according to the applications.

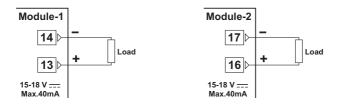
5.2 EMO-910 SSR Driver Module Connection



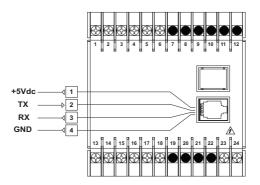


Fuses must be selected according to the applications.

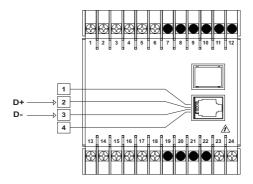
5.3 EMO-920 Digital (Transistor) Output Module Connection

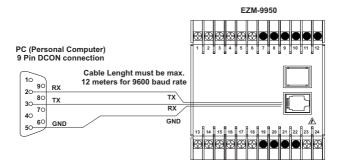


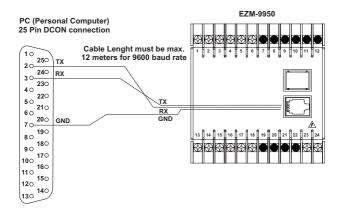
RS-232 Terminal Definitions



RS-485 Terminal Definitions

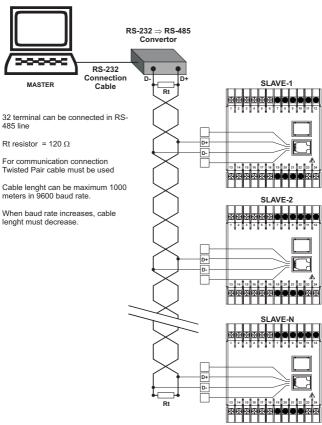






6.2 Connection for RS-485 Serial Communication

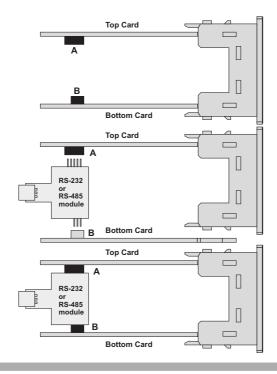
PC(Personal Computer)



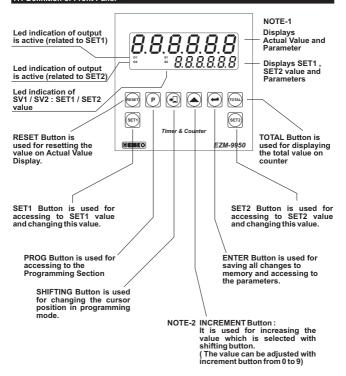
6.3 Installing RS-232 / RS-485 Serial Communication Modules to the Device

Pull the cover case with your hand through rear side as explained in "Installing and Pulling Out Output Modules" section. Pull the modules in Module-1 and Module-2 socket through rear side. Separate supply card which is at the bottom of the equipment by lifting the locking tabs located on front panel. Pay attention to cable connection between top and bottom cards. Damages in this cable makes the equipment not to work.

RS-232 or RS-485 module is plugged into socket signed as A and B. Hold the equipment to be it's front panel is on your right, communication socket is on your left and module connection socket with 5 terminals on above. Plug in module connection socket with 5 terminals to the socket on Top Card. Do the same things for terminal socket in bottom card and connection socket with 3 terminals. Plug in bottom card to the place in front panel. Install the modules which are pulled out to Module-1 and Module-2 socket. Replace the cover case by taking care of the terminal numbers should be at right position.



7.1 Definition of Front Panel



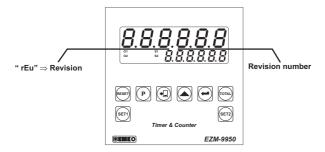
NOTE-1: Total count value is 12 digits in Counter / "Totalizer Counter" function

NOTE-2: In Counter / "Totalizer Counter" function if SET1 operation form selection parameter \(\begin{array}{c} r-c-2 \end{array} \) is \(\begin{array}{c} \overline{\text{UICOL}} \end{array}, then SET1 can be negative. While most significant digit (6th digit) of SET1 value is changed from 0 to 9 with increment button, after 9, "-" character is on the most significant digit (6th digit) of SET1 value and Enter button is pressed, SET1 value becomes negative.

7.2 Power On Observation of EZM - 9950 Programmable Timer & Counter and Software Revision on the Display

When power is applied to the device, software revision number of the controller is momentarily illuminated on actual value display. Then operation screen is observed.

When power on, view of the screen is shown below:







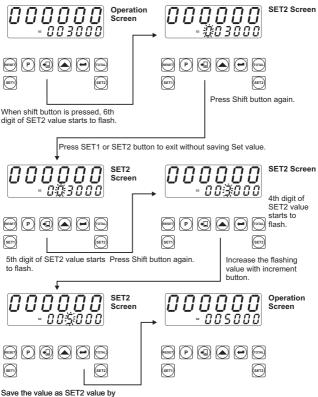


Operation Screen is shown



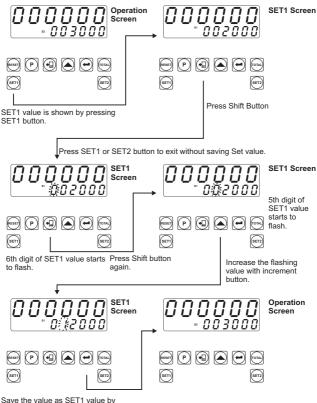
If there is an unexpected situation while opening the device, power off the device and inform a qualified personnel.

Changing SET2 value in Counter / "Totalizer Counter" functions



pressing Enter button.

If Pro-2B Reset and Set Protection parameter is [10002], [10005] or [10005] then SET2 value can not be changed. For details, refer to parameters section.



Save the value as SET1 value by pressing Enter button.

If Pro-2B Reset and Set Protection parameter is [00002], [00003] or [00003], then SET1 value can not be changed. For details, refer to parameters section.

7.4 Resetting Count Value and Observing Total Count Value in COUNTER / "TOTALIZER COUNTER" Function Operation Operation 10 0 0 0 0 0 0 0 1 Screen Screen After count value is reset. press TOTAL button. RESET (P) (42) (A) (-4) RESET P 10 A TOTAL Count value is reset and added to the total count value when RESET button is pressed. 000<u>0</u>00 000000 -000000 TOTAL Screen Screen P P

Continue to press TOTAL button. When user stops pressing Total button, operation screen is shown. If RESET button is pressed while TOTAL button is pressing, total count value is reset.

Total count value is 12 digits.

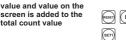
When user stops pressing the buttons, operation screen is shown.

Note-1: If manual reset is applied when counting direction parameter Pro- 19 Is 00000 1 difference between SET2 value and value on the screen is added to the



Operation Screen

Note-2: Becoming zero of count value is for if counting direction parameter Pcg- 19 Is 000000, if counting direction parameter Pro- 19 direction parameter Fra ls [1] [1] count value ¬ becomes equal to SET2 value





If Pro-28 Reset and Set Protection parameter is 00000 for 000003 then total count value can not be reset. For details, refer to parameters section.



RESET operation can be realized by Reset button or applying signal to the RESET input. These two operations are named MANUAL RESET in parameters section. At the end of the MANUAL RESET operation, if counting direction parameter Pro- 19 is 000000 then count value becomes 000000 . If counting direction parameter Pro- 19 is 00000 I then count value becomes equal to SET2 value.



7.5 COUNTER / "TOTALIZER COUNTER" Parameters

SET1

SET value for Output-1. Control of the Output-1 is done according to this value. It can be adjusted from [000000] to

If SET1 operation form selection parameter P_{-0} - 22 is selected operation with offset 00000 i, it can be adjusted from -99999 to 999998

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be adjusted from [000000] to [999998]

P-0-0 1 1

Input Types and Functions

Upcount on rising edge of Ch-Ainput(INC)

Downcount on rising edge of Ch-Ainput(DEC)

Upcount on rising edge of Ch-A input and downcount on rising edge of Ch-B input (INC / DEC)

Upcount on rising edge of Ch-A input when Ch-B is at 0, downcount on rising edge of Ch-A input when Ch-B is at 1.(UP/DOWN)

mmmm x1 phase shifting (for incremental encoders)

x2 phase shifting (for incremental encoders)

x4 phase shifting (for incremental encoders)

Pro-04

Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

It can be adjusted from \(\begin{align*} \text{TOOOD} \) to \(\begin{align*} \text{TOOOD} \) then there is no time protection for Ch-A and Ch-B. If the parameter value is adjusted \(\begin{align*} \text{TOOOD} \) or \(\begin{align*} \text{TOOOD} \) then Reset and Pause protection times are accepted as 2 msec.

Pro-05

Output Functions

Manual Reset-1. Device continues to count till manual reset is applied.
Output-2 pulse time Pro-17 is not considered.

Manual Reset-2. Device continues to count till count value reaches to SET2 value. For starting to count again, manual reset input must be active. Output-2 pulse time | P⁻o - ∏ is not considered.

Manual Reset-3. It operates like Manual Reset-1. Only difference, output-2 pulse time Pro-17 is considered.



In operation with Manual or Automatic Reset, at the end of the reset operation, if counting direction parameter $[P_{-n}-19]$ is $\boxed{0.00000}$ $(0\Rightarrow P)$, count value becomes $\boxed{0.00000}$. If $[P_{-0}-19]$ is $\boxed{0.00000}$ $(P\Rightarrow 0)$, count value becomes SET2.



- Automatic Reset-1. Count value is reset when it reaches to SET2 value (For 0⇒P). Count value is added to total count value and device starts to count from 000000 Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value becomes zero (for 0⇒P) at the end of output-2 pulse time Pro- 17 And count value is added to total count value. Device starts to count from [DDDDDD] 10000051 Automatic Reset-3. Count value becomes zero (for 0⇒P) when it reaches to SET2 value and count value is added to total count value. Device starts to display, count value is shown at the end of output-2 pulse time Pro - 17 Automatic Reset-4. Counting is continued when count value reaches to SET2 value.Count value becomes zero (for 0⇒P) at the end of Output-2 pulse Pro- 17 time and it is added to total count value. Device Automatic Reset-5. Counting is continued till manual reset is active. Output-רססססס 1 and Output-2 pulse times (Pro-15) and Pro-17) are not considered. It is preferred if upcount and downcount are done at the same time. In operation with Manual or Automatic Reset, at the end of the reset operation, if counting direction parameter Pro-19 is 000000 (0⇒P), count value becomes 000000. If Pro-19 is 00000 1(P⇒0), count value becomes SET2. Pro- 14 Operation form for Output-1 Output - 1 Normally non-energised 00000 1 Output - 1 Normally energised IPco- 15 Operation form for Output-2 Output - 2 Normally non-energised nnnnnOutput - 2 Normally energised Pro- 16 **Output-1 Pulse Time** Energising time for Output-1. It can be adjusted from [000000] to [009999] If it is \(\begin{aligned} \Pi & \p **Output-2 Pulse Time** Pro- 17 Energising time for Output-2. It can be adjusted from \$\omega\$ 00000 to \$\omega\$ 009999 If it is \[\begin{align*} \pi \ Selection of counting direction Pro- 19
 - For details on parameters, refer to Section 8 (Program Parameters).

<u> Pro-20</u>	Point Position for display
000000	No point
00000 1	Between first and second digits
000002	Between second and third digits
000003	Between third and fourth digits
000004	Between fourth and fifth digits
Pro-21	Saving Count Value (Power down back-up)
000000	Count value is saved to memory when power is off and restored on power up.
00000 1	Count value is not saved to memory when power is off
Pro-22	Selection of SET1 Operation Form
000000	Operating without offset. It can be adjusted from [33333] to [999998]
00000 1	Operating with offset. SET1 can be adjusted SET1 = SET2+SET1
Pro-23	Slave Address
	Device address for serial communication bus. It can be adjusted from @@@@@ I to @@@24기
Pro-24	Selection of Modbus Protocol Type
000000	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
Pro-25	Parity
000000	No parity
00000 1	Odd parity
000002	Even parity
Pro-26	Baud Rate
[000000]	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate



Pro-27	Stop Bit
000000	1 Stop Bit
00000 1	2 Stop Bits
Pro-28	Reset and Set protection (Accessing from front panel)

There is no Reset and Set protection

Reset Button protection is active

SET1 and SET2 protection is active

Reset Button, SET1 and SET2 protection is active (Full protection)

SET1 protection is active

SET2 protection is active

Multiplication Coefficient

Program Password

It is used for accessing to the program parameters.

It can be adjusted from 000000 to 009999 . If it is 000000, there is no password protection.

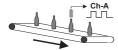


7.5.1 COUNTER / "TOTALIZER COUNTER" Applications Examples

FXAMPI F-1:

There is a production band like in diagram below. Bottles are perceived by a proximity sensor in Ch-A. If

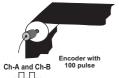
Pro-01=000000; Pro-30=0 (0000);



Counting the bottles is done with upcount by using only Ch-A input. When user reset count value with manual reset, count value is added to total count value.

FXAMPI F-2:

There is a cloth workbench. An encoder with 100 pulse is connected to this system. The encoder is connected to Ch-A and Ch-B inputs.



You wish to display 200 in actual value display for a drive pulley going forward of 100 cm.lf you want to display cloth length in actual value display, you must adjust coefficient parameter Promatuli like in below:

= Measured cloth length Value on the screen

Pro-∃0 Coefficient must be = 100/200 = "00.5000"

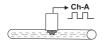
After adjustment of coefficient, calculated value is cloth length and you can see this value in actual value display.

If you want to display the speed of the drive pulley as dm instead of cm $P_C = 2$ point position for display parameter must be 00000. If if m instead of cm, this parameter must be 00000.

EXAMPLE-3:

There is a system like in the diagram below. Ch-A is used for measuring the flow. If

Pro-01=000000 Pro-30=0 (0000

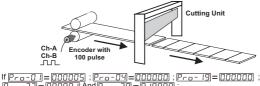


In this application, total amount of flow is measured. If it is known how many pulses are being sent for each liter from the sensor in Ch-A we can measure the desired value by changing the Pro-30 parameter.

For example if sensor gives 10 pulses for 1 liter fluid flow and we want to observe the liquid quantity as liter, coefficient parameter $\frac{P_{P_0}-3D}{P_{P_0}-3D}$ parameter value must be $\frac{P_{P_0}-3D}{P_0}=11.t(10 \text{ pulse}="0.1000"}$

EXAMPLE - 4:

There is a cutting unit below. 100-pulse encoder is connected to Ch-A and Ch-B inputs.



Pro-22 = 00000 | And Pro-30 = 0 0000 |;

If Pro-22 parameter is 00000 |, then device operates with offset. If SET1 is negative value, then Output-1 will be active in SET2-SET1. This option offers us to solve wrong cutting problem

(SET1=SET1+SET2)

For example ;if SET1 = -000100; SET2 = 000500; then SET1 = -100+500 = 400

If more sensitivity is needed, $P_{CO} - Q_{CO}$ parameter can be selected $Q_{CO} = Q_{CO} = Q_{CO}$ or $Q_{CO} = Q_{CO} = Q_{CO}$

For example, while x1 phase shifting counting is performed in a system with a cutting unit as shown above, a 100-pulse encoder is connected to Ch-A and Ch-B inputs. If the system is advanced 100 cm for 50 encoder pulses, so it is advanced 2 cm with 1 encoder pulse.

When x2 phase shifting counting is performed, for the system is being advanced 100 cm, 100 encoder pulses are needed. In this case, the system is advanced 1 cm with 1 encoder pulse.

When x4 phase shifting counting is performed, for the system is being advanced 100 cm, 200 encoder pulses are needed. In this case, the system is advanced 0.5 cm with 1 encoder pulse.

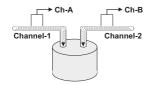
Sensitivity of the system is changed from 2 cm to 0.5 cm.

on the speedy mechanic, by reaching slowly to the target.

EXAMPLE-5:

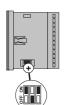
There are two sensors in Ch-A and Ch-B inputs for determining the amount of the liguid in Channel-A and Channel-B. Multiplication coefficient parameter $[\frac{p_{r,q}-3}{3}]$ is adjusted to converts the pulses to observe the amount of the liquid exactly in the actual value screen. (For example liter)

For observing total amount of liquid Pro-01 must be 000003



If the tank is filled with liguid 20 liters from Channel-1 and 40 liters from Channel-2, 60 liters is observed in actual value screen.

If Output-1 controls the Channel-1, Output-2 controls the Channel-2, SET1 is 20 and SET2 is 40, then it is possible to close the system after filling the tank with 20 liters from Channel-1 and 40 liters from Channel-2



7.6 BATCH COUNTER Parameters

SET1

SET value for Output-1. Control of the Output-1 is done according to this value. It can be adjusted from [000000] to [999990]

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be adjusted from []]]]]]]]]] to []99998]



Input Types and Functions

Upcount on rising edge of input Ch-A (INC)

Downcount on rising edge of input Ch-A(DEC)

Upcount on rising edge of input Ch-A and downcount on rising edge of input Ch-B (INC/DEC)

Upcount on rising edge of input Ch-A and Ch-B (INC / INC)

Upcount on rising edge of Ch-A input when Ch-B is at 0, downcount on rising edge of Ch-A input when Ch-B is at 1.(UP/DOWN)

MARCH x1 phase shifting (for incremental encoders)

x2 phase shifting (for incremental encoders)

x4 phase shifting (for incremental encoders)



Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

It can be adjusted from \$\tilde{\text{DDDDD}}\$ to \$\tilde{\text{DDDDDD}}\$ msec. If it's adjusted to \$\tilde{\text{DDDDDD}}\$ then there is no time protection for Ch-A and Ch-B. If the parameter value is adjusted \$\tilde{\text{DDDDD}}\$ or \$\tilde{\text{DDDDD}}\$ then Reset and Pause protection times are accepted as 2 msec.



When SET1 value is shown on the screen if MANUAL RESET is applied, batch count value, when SET2 value is shown on the screen if MANUAL RESET is applied, normal count value becomes zero.





Pro-OS	Output Functions
000000	Manual Reset. BATCH counting operation continues until manual reset input is active.
00000 1	Automatic Reset.BATCH counting operation continues until Batch count value reaches to SET1 value.When Batch count value is equal to SET1 value,Batch count value becomes zero (for $0 \Rightarrow P$) and device starts to count again.
Pro- 14	Operation Form of Output-1
000000	Output - 1 Normally non-energised
00000 1	Output - 1 Normally energised
Pro- 15	Operation Form of Output-2
000000	Output - 2 Normally non-energised
00000 1	Output - 2 Normally energised
Pro- 16	Output-1 Pulse Time
(1 0 10)	Energising time for Output-1. It can be adjusted from @@@@@@to @@9999 If it is @@@@@@ , then it operates indefinitely.
Pro- 17	Output-2 Pulse Time
	Energising time for Output-2. It can be adjusted from [] to [] 19999 If it is [] 199
Pro- 19	Selection of counting direction
000000	Upcount(0⇒Preset)
00000 1	$Downcount(Preset \! \Rightarrow \! 0)$
Pro-20	Point Position for display
000000	No point
00000 1	Between first and second digits
000002	Between second and third digits
000003	Between third and fourth digits
000004	Between fourth and fifth digits
Pro-2 1	Saving Count Value (Power down back-up)
000000	Count value is saved power is off and restored on power up.
00000 1	Count value is not saved to memory when power is off
Pcn-23	Slave Address
	Device address for serial communication bus. It can be adjusted from 000001 to 000247



Selection of Modbus Protocol Type Pro-24 MODBUS ASCII communication protocol is selected. MODBUS RTU communication protocol is selected Parity 000000 No parity Odd parity כחחחחח Even parity P-0-2 **Baud Rate** 1200 Baud Rate 2400 Baud Rate 4800 Baud Rate 9600 Baud Rate ппппппч 19200 Baud Rate P-0-2 Stop Bit 000000 1 Stop Bit 100000 2 Stop Bits Reset and Set protection (Accessing from front panel) There is no Reset and Set protection Reset Button protection is active SET1 and SET2 protection is active Reset Button, SET1 and SET2 protection is active (Full protection) ПППППЧ SET1 protection is active SET2 protection is active P-n-30 Multiplication Coefficient Count value is multiplied with this value. It can be adjusted from [] [] [] [] to. 999999 .If it is 0 10000 , it has no effect. Pro-P5 **Program Password** It is used for accessing to the program parameters. It can be adjusted from 000000 to 009999 . If it is 000000, there is no password protection.

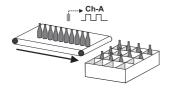


7.6.1 BATCH COUNTER Applications Examples

FXAMPI F-1:

There is a production band like in diagram below. Bottles are perceived by a proximity sensor in Ch-A. If

Pro-01=000000; Pro-30=0 (0000);



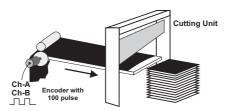
Device is used in a packing line as shown on the left. Bottles must be counted into packs of 4 bottles and dispatched in a box containing a batch of 4 packs. According to this, SET1 and SET2 are defined 4.4 pieces of packet which contain a batch of 4 series are allowed to be formed.

If Pro-05 = 00000 (Automatic Reset-1); after arranging the bottles in a box as shown on the left, output-1 will be active and it stops the system. Batch count value is reset and it will be ready to count the new series.

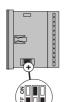
EXAMPLE-2:

There is a cloth workbench. An encoder with 100 pulse is connected to this system. The encoder is connected to Ch-A and Ch-B inputs.

If <u>Pro-0 |= 000005</u>; <u>Pro-04</u>=000000; |Pro-19=000000 And |Pro-30=0 10000);



Coefficient parameter is adjusted to be able to observe the cloth length in actual value screen. If we want to be cut the cloth in same length at 5 m and stopped the system when 40 pieces of 5 m cloths are formed, SET1 must be 40 and SET must be 5.



12-n-NS

7.7 TIMER Parameters

SET1 ascording to this value. It can be changed by time unit and scale selection parameter [P_{T,D} = \(\frac{1}{2} \) \]

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be changed by time unit and scale selection parameter $P_{CQ} = 0.5$

ro-05	Time Unit and Scale Selection
000000	Hour / Minute It can be adjusted from 000000 to 009959
00000 1	Minute / Second It can be adjusted from [][][][][][][][][][][][][][][][][][][]
000002	Second / Millisecond It can be adjusted from [00000] to [009999]
000003	Hour/Minute It can be adjusted from [000000] to [002359]
000004	Hour It can be adjusted from [00000] to [099999]
000005	Minute It can be adjusted from \$\text{DDDDD}\$ to \$\text{D99999}\$
000006	Second It can be adjusted from [] 100000 to [] 1999999

Output Functions

Manual Reset-1. Device continues to count till manual reset is applied.

Output-2 pulse time Pro-17 is not considered.

Manual Reset-2. Device continues to count till count value reaches to SET2 value. For starting to count again, manual reset input must be active. Output-2 pulse time [Prart] is not considered.

Manual Reset-3. It operates like Manual Reset-1. Only difference, output-2 pulse time Pro-17 is considered.

Automatic Reset-1. Count value becomes zero (0⇒P) when it reaches to SET2 value. Count value is added to total count value and device starts to count from □□□□□□□

Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value is becomes zero (0⇒P) at the end of output-2 pulse time |P-□ - |∏ And device starts to count again.



000005	Automatic Reset-3. Count value becomes zero (0⇒P) when it reaches to SET2 value. Device starts to count again. Meanwhile, SET2 value is shown in actual value display, count value is shown at the end of output-2 pulse time
000006	Automatic Reset-4. Counting is continued when count value reaches to SET2 value.Count value is becomes zero $(0\Rightarrow P)$ at the end of Output-2 pulse time $Pco-II$. Device starts to count again.
000007	Automatic Reset-5. When count value reaches to SET2 value, SET1 changes position, count value becomes zero (for $0\Rightarrow P$) Output-1 and Output-2 does not change position position until count value reaches to SET2 value.
(į) counti	ration with Manual or Automatic Reset, at the end of the reset operation, if ng direction parameter P_{CO-1} 9 is 000000 0 (0 \Rightarrow P), count value les 000000 1. If P_{CO-1} 9 is 000000 1 (P \Rightarrow 0), count value becomes SET2.
Pro- 14	Operation form for Output-1
000000	Output - 1 Normally non-energised
00000 1	Output - 1 Normally energised
Pro- 15	Operation form for Output-2
000000	Output - 2 Normally non-energised
00000 1	Output - 2 Normally energised
Pro- 16	Output-1 Pulse Time
	Energising time for Output-1. It can be adjusted from $\boxed{000000}$ to $\boxed{009999}$ If it is $\boxed{000000}$, it operates indefinitely.
Pro- 17	Output-2 Pulse Time
	Energising time for Output-2. It can be adjusted from \$\text{TDDDDD}\$ to \$\text{DDDDDDD}\$, it operates indefinitely.}
Pro- 19	Selection of counting direction
000000	Upcount(0⇒Preset)
00000 1	$Downcount(Preset \!\Rightarrow\! 0)$
Pro-21	Saving Count Value (Power down back-up)
000000	Count value is saved when power is off and restored on power up.
00000 1	Count value is not saved to memory when power is off
Pro-23	Slave Address
110-63	Device address for serial communication bus. It can be adjusted from [] 10000 to [] 10002년기

Selection of Modbus Protocol Type 000000 MODBUS ASCII communication protocol is selected. MODBUS RTU communication protocol is selected Parity No parity Odd parity Even parity P-0-21 **Baud Rate** 1200 Baud Rate 2400 Baud Rate 4800 Baud Rate 9600 Baud Rate 19200 Baud Rate P-0-2 Stop Bit 000000 1 Stop Bit 00000 2 Stop Bits Reset and Set protection (Accessing from front panel) [000000] There is no Reset and Set protection Reset Button protection is active Reset Button, SET1 and SET2 protection is active (Full protection) □□□□□□ SET1 protection is active ΠΠΠΠΠΓ SET2 protection is active P-n-P5 **Program Password** It is used for accessing to the program parameters. It can be adjusted from 000000 to 009999 . If it is 000000, there is no



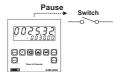


7.7.1 Timer Applications Examples

EXAMPLE-1:

There is a switch for giving start and stop signal on PAUSE input.

If (Pro-05) = (00000 i);

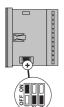


When switch is "On", counting is started (Minute / second). When switch is "Off", counting is stopped. Time between opening and closing of the switch is observed on actual value screen.

Expired time can be reset with manual reset. If total operation time is wanted to be observed on the screen, manual reset is not applied and after Start/Stop operation counting is started from the last count value.

NOTE: If output-1 and output-2 is wanted to be used as an alarm output;

For example SET1 = 10.00; SET2= 30.00 and $\boxed{P_{-D} - 0.5} = \boxed{00000}$ Device starts to count (Minute / second) when switch is "On". It is possible to have a warning when SET1 and SET2 times are expired and stopping the alarm at the end of the Output-1 and Output-2 pulse times. $\boxed{P_{-D} - 1.5}$ And $\boxed{P_{-D} - 1.7}$



7.8 FREQUENCYMETER / TACHOMETER Parameters

SET1

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be adjusted from []]]]]] to []99998]



Selection of Measurement Method

000000

Frequency or cycle is calculated by measuring cycle time of the signals in Ch-Ainput

00000 1

Frequency or cycle is calculated by counting the pulses in Ch-A input during the time is set in measurement period parameter Pro-D



Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.



Time Out (Input Signal Reset Time)

The actual value is reset, if there is no signal in Ch-Ainput during this time It can be adjusted from [00000 i] to [000099]



Measurement Period

Number of pulses is counted during this time
It can be adjusted from 00000 If to 000999



Output-1 Function

ΠΠΠΠΠΠ Output-1 is latched

Output-1 is latched. It does not change position until manual reset is applied.

Non-latched with hysteresis output is selected.

000002

Output-1 is an alarm output. For details, refer to Output-1 Alarm functions parameter $|P_{\Gamma,Q} - I|$.



Pro- 10	Output-2 Function
000000	Output-2 is latched. It does not change position until manual reset is applied.
000001	Non-latched with hysteresis output is selected.
Pro- ! !	Alarm Functions for Output-1
	If Output-1 function parameter $\begin{tabular}{ll} Pro-$\mathbb{Z}_2$ & is & $\mathbb{Z}_2^* = \mathbb{Z}_2^*$ & , Output-1 \\ becomes active according to this parameter & & & & & & \\ \end{tabular}$
000000	High Alarm.
00000 1	Low Alarm.
[20000]	Deviation High Alarm.
000003	Deviation Low Alarm.
000004	Deviation Band Alarm.
Pro- 12	Hysteresis for Output-1
LL0- 1C	Hysteresis for Output-1. It is used if Output-1 is non-latched.
	It can be adjusted from 000000 to 050000
Pro- 13	Hysteresis for Output-2
	Hysteresis for Output-2. It is used if Output-2 is non-latched. It can be adjusted from 000000 to 050000
	,
Pro- 14	Operation form for Output-1
000000	Output - 1 Normally non-energised
00000 1	Output - 1 Normally energised
Pro- 15	Operation form for Output-2
000000	Output - 2 Normally non-energised
00000 (Output - 2 Normally energised
Pro- 16	Output-1 Pulse Time
	Energising time for Output-1. It can be adjusted from 000000 to 009999
	If it is []]]]], then it operates indefinitely.
Pro- 17	Output-2 Pulse Time
	Energising time for Output-2. It can be adjusted from [] to [] 1000000 to [] 10000000 to [] 100000000000000000000000000000000000



Pro- 18	Start of Controlling
000000	Controlling is started when the device is energised
00000 1	Controlling is started when count value reaches to SET1 value.
000002	Controlling is started when count value reaches to SET2 value.
Pro-20	Point Position for display
[000000]	No point
00000 1	Between first and second digits
000002	Between second and third digits
000003	Between third and fourth digits
000004	Between fourth and fifth digits
Pco-23	Slave Address
23	Device address for serial communication bus. It can be adjusted from DDDDD 1 to DDDZY1
Pro-24	Selection of Modbus Protocol Type
000000	MODBUS ASCII communication protocol is selected.
00000 1	MODBUS RTU communication protocol is selected
Pro-25	Parity
000000	No parity
00000 1	Odd parity
000002	Even parity
Pro-26	Baud Rate
000000	1200 Baud Rate
00000 (2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate
Pro-27	Stop Bit
000000	1 Stop Bit
00000 1	2 Stop Bits



Pro-28	Reset and Set protection (Accessing from front panel)
000000	There is no Reset and Set protection
00000 1	Reset Button protection is active
000002	SET1 and SET2 protection is active
000003	Reset Button, SET1 and SET2 protection is active (Full protection)
000004	SET1 protection is active
000005	SET2 protection is active
	F

Frequency / Cycle Multiplication Coefficient Count value is multiplied with this value. It can be adjusted from [00000] to [00000] Multiplication Coefficient

Count value is multiplied with this value. It can be adjusted from \$\textstyle{00000}\$ to. \$\text{99999}\$. If it is \$\text{00000}\$, it has no effect.

Program Password It is used for accessing to the program parameters. It can be adjusted from 000000 to 009999 . If it is 000000, there is no password protection.



7.8.1 FREQUENCYMETER / TACHOMETER Applications Examples

 $Two \ different \ methods \ are \ used \ in \ Frequency meter / \ Tachometer \ function;$

Method -1: To get frequency or cycle value by measuring the revolution time

(This method is used if the sensor sends one pulse per revolution)

Method -2: To get frequency or cycle value by counting the pulses during the time is set in Pro-□0 parameter

Method -1:

If Pro-03 is 000000;

 $\label{eq:measuring} \textit{Measuring starts on rising edge of Ch-Ainput. Time (T) is between two rising edge.}$



If P_{-0} -29 parameter is 00001, P_{-0} -30 parameter is 0000, then speed is measured cycle per second.

For measuring the speed cycle per minute, P_{CO} parameter must be 000050 For measuring the speed cycle per hour, P_{CO} parameter must be 003500

EXAMPLE-1:

There is a cloth workbench as shown below:

When P_{-0} = 29 parameter is 000001, P_{-0} = 30 parameter is 00000, cloth is advanced 80 cm per revolution and 20 cycle / sec is observed on the display.

User can observe cloth length, 80 cm, on the display by changing the Pro-29 and Prameter



 $\frac{\text{Pro-30}}{\text{Pro-29}} = \frac{\text{Cloth Length in one revolution}}{\text{Pro-29}} * \text{Value on the display (f)}$

If <u>Pro-dy</u> = 1 <u>Pro-dy</u> Multiplication coefficient = 80/20 = 4 After adjustment of the parameter, 80 cm / sec is observed on the display.

For dm/sec, point position for display parameter $P_{CO} = 20$ must be 0000000 for m/sec, point position for display parameter $P_{CO} = 20$ must be 00000000

For cm/minute, P_{CO} - 29 parameter must be 00050 For cm/hour, P_{CO} - 29 parameter must be 003500



This method must be used if speed is over 100 cycle / second

Method -2:

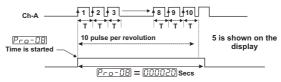
If Pro-03 parameter is 00000 1

Pulses in Ch-A input is counted during time is set in Pro-B parameter. Average time for one pulse is calculated.



FXAMPI F-2:

For one revolution of cylinder 10 pulse is applied in Ch-A input during Pro-08 = 000020

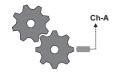


If 10 pulse is applied during 2 secs;

T = 2/10 = 0.2sec f = 1/T f = 5 cycle / sec is shown on the display

If P_{-o} parameter is 000001 and P_{-o} and parameter is 00000 , speed is measured as cycle per second.

For cycle / minute, P_{-0} - 29 parameter must be 0.0050 For cycle / hour, P_{-0} - 29 parameter must be 0.03500



FXAMPI F-3:

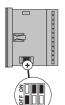
8 pulse is applied per revolution during Pro-08=000005 If Pro-29 parameter is 000001 and

Pro-30 Parameter is 0.0000, speed of the system (cycle per second) is calculated as shown below:

If 8 pulse is applied during 0.5 sec;

T = 0.5/8 = 0.0625sec f= 1/T f = 16 cycle / sec is shown on the display

For cycle / minute, Pro - 29 parameter must be []]] For cycle / hour, [Pro - 29] parameter must be []]]



7.9 CHRONOMETER Parameters

SET1

SET value for Output-1. Control of the Output-1 is done according to this value. It can be changed by time unit and scale selection parameter $P_{CQ} = US$

SET2

SET value for Output-2. Control of the Output-2 is done according to this value. It can be changed by time unit and scale selection parameter [Pro-075]

Pco-02 In

Input Type and Function Selection for Chronometer

Period measurement of signals in Ch-A input

Pulse time measurement of signals in Ch-Ainput

Sum of the time difference between Ch-A and Ch-B inputs rising edges

Pro-04

Pulse Time of Ch-A, Ch-B, Reset and Pause Inputs

It is used to protect against the electrical contact debounce or the signal that is less than the determined pulse time.

It can be adjusted from \(\begin{align*} \text{DDDDDD} \) to \(\begin{align*} \text{DDDDDD} \\ \text{the parameter} \) when there is no time protection for Ch-A and Ch-B. If the parameter value is adjusted \(\begin{align*} \text{DDDDD} \\ \text{DDDDDD} \\ \text{DDDDDD} \\ \text{The Reset and Pause protection times are accepted as 2 msec.} \end{align*}

Pro-05

Time Unit and Scale Selection

OOOOO Hour/Minute

It can be adjusted from 000000 to 009959

□□□□□ | Minute / Second

It can be adjusted from 000000 to 009959

□□□□□□ Second / Millisecond

It can be adjusted from 000000 to 009999

□□□□□∃ Hour/Minute

It can be adjusted from 000000 to 002359

000004 Hou

It can be adjusted from 000000 to 099999

00005 Minute

It can be adjusted from 000000 to 099999

DDDD Second

It can be adjusted from 000000 to 099999





Pro-05	Output Functions
000000	Manual Reset-1. Device continues to count till manual reset is applied. Output-2 pulse time $P = o = 1$ is not considered.
00000 1	Manual Reset-2. Device continues to count till count value reaches to SET2 value. For starting to count again, manual reset input must be active. Output-2 pulse time $\boxed{\Pr_{\mathcal{D}} - !}$ is not considered.
000002	Manual Reset-3. It operates like Manual Reset-1. Only difference, output-2 pulse time Pro-17 is considered.
000003	prop:prop:prop:prop:prop:prop:prop:prop
000004	Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value becomes zero (for $0 \Rightarrow P$) at the end of output-2 pulse time $P = P = P$ And device starts to count again.
000005	$\label{eq:Automatic Reset-3.} Automatic Reset-3. Count value becomes zero (for 0 \Rightarrow P) when it reaches to SET2 value. Device starts to count again. Meanwhile, SET2 value is shown in actual value display, count value is shown at the end of output-2 pulse time.$
000006	Automatic Reset-4. Counting is continued when count value reaches to SET2 value. Count value becomes zero (0 \Rightarrow P)at the end of Output-2 pulse time $\boxed{\text{Pro-1}}$ device starts to count again.
000007	Automatic Reset-5. When count value reaches to SET2 value, SET1 changes position, count value becomes zero (0 \Rightarrow P). Output-1 and Output-2 do not change position, until count value reaches to SET2 value.
/ In ope	ration with Manual or Automatic Reset, at the end of the reset operation, if
count become	ing direction parameter $[P_{ro}-1]$ is $\boxed{0.00000}$ $(0\Rightarrow P)$, count value nes $\boxed{0.00000}$. If $\boxed{P_{ro}-1}$ is $\boxed{0.00000}$ $(P\Rightarrow 0)$, count value becomes SET2.
count becom	ing direction parameter P_{ro} - 19 is 000000 (0 \Rightarrow P), count value
Pro-14	ing direction parameter $P_{-o} - P$ is $P_{-o} - P$, count value nes $P_{-o} - P$ is $P_{-o} - P$, count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised
Pro- 14 00000	ing direction parameter $P_{-o} - 19$ is $00000000000000000000000000000000000$
Pro-14	ing direction parameter Pro-19 is 00000 (0⇒P), count value nes 000000. If Pro-19 is 00000 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2
Pro-14 00000 00000 Pro-15	ing direction parameter Pro-19 is 00000 (0⇒P), count value nes 000000. If Pro-19 is 00000 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2
Pro- 14 000000 000001 Pro- 15	ing direction parameter Pro-19 is 10001 (0⇒P), count value nes 100001 if Pro-19 is 10001 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally non-energised Output-2 Normally energised Output-1 Pulse Time
Pro- 14 000001 Pro- 15	ing direction parameter Pro-19 is 10001 (0⇒P), count value nes 100001. If Pro-19 is 10001 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally non-energised Output-2 Normally non-energised Output-2 Normally energised
Pro- 15 00000 00000 Pro- 15	ing direction parameter Pro-19 is 10000 (0⇒P), count value nes 100000. If Pro-19 is 10000 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally energised Output-2 Normally energised Output-1 Normally energised Output-1 Pulse Time Energising time for Output-1. It can be adjusted from 1000000 to 1009999
Pro- 14 000001 Pro- 15	ing direction parameter Pro-19 is 10000 (0⇒P), count value nes 100000. If Pro-19 is 10000 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally energised Output-2 Normally energised Output-1 Pulse Time Energising time for Output-1. It can be adjusted from 1000000 to 1000000 If it is 10000000 then it operates indefinitely.
Pro- 15 00000 00000 Pro- 15	ing direction parameter Pro-19 is 10000 (0⇒P), count value nes 100000 if Pro-19 is 10000 (P→0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally non-energised Output-2 Normally energised Output-1 Pulse Time Energising time for Output-1. It can be adjusted from 1000000 to 10000000 Output-2 Pulse Time Energising time for Output-2. It can be adjusted from 10000000 to 100000000000000000000000000
Pro- 19 Pro- 15 Pro- 15 Pro- 15	ing direction parameter Pro-19 is 10001 (0⇒P), count value nes 100001. If Pro-19 is 10001 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally non-energised Output-1 Pulse Time Energising time for Output-1. It can be adjusted from 100001 to 109999 lift its 100001, then it operates indefinitely. Output-2 Pulse Time Energising time for Output-2. It can be adjusted from 1000010 to 109999 lift its 1000000 to 1009999 lift its 10000000 to 1009999 lift its 100000000 to 1009999 lift its 1000000000000000000000000000000000000
Pro- 19 Pro- 19	ing direction parameter Pro-19 is 10000 (0⇒P), count value nes 100000. If Pro-19 is 10000 (P⇒0), count value becomes SET2. Operation form for Output-1 Output-1 Normally non-energised Output-1 Normally energised Operation form for Output-2 Output-2 Normally non-energised Output-2 Normally energised Output-1 Pulse Time Energising time for Output-1. It can be adjusted from 1000000 to 1000000 if it is 10000000 if it is 100000000000000000000000000000000000

Pro-21	Saving Count Value (Power down back-up)
[000000]	Count value is saved to memory when power is disconnected and restored on power up. $ \\$
00000 1	Count value is not saved to memory when power is disconnected
Pro-23	Slave Address
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Device address for serial communication bus. It can be adjusted from 000001 to 000247
Pro-24	Selection of Modbus Protocol Type
000000	MODBUS ASCII communication protocol is selected.
00000	MODBUS RTU communication protocol is selected
Pro-25	Parity
000000	No parity
00000	Odd parity
000002	Even parity
Pro-26	Baud Rate
000000	1200 Baud Rate
00000 1	2400 Baud Rate
000002	4800 Baud Rate
000003	9600 Baud Rate
000004	19200 Baud Rate
Pro-27	Stop Bit
000000	1 Stop Bit
00000 (2 Stop Bits
Pro-28	Reset and Set protection (Accessing from front panel)
000000	There is no Reset and Set protection
00000 1	Reset Button protection is active
000002	SET1 and SET2 protection is active
000003	ResetButton,SET1andSET2protectionisactive(Fullprotection)
000004	SET1 protection is active
000005	SET2 protection is active
Pro-PS	Program Password
	It is used for accessing to the program parameters. It can be adjusted from [00000] to [009999]. If it is [000000], there is no password protection.

password protection.

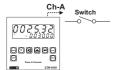


7.9.1 Examples About CHRONOMETER Applications

FXAMPI F-1:

There is a switch for giving start and stop signal on Ch-Ainput.

Pro-02 = 000001; Pro-04 = 000050; Pro-05 = 000001 iken;



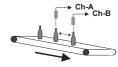
When switch is "On", counting is started (Minute / second). When switch is "Off", counting is stopped. Time between opening and closing of the switch is observed on actual value screen.

Expired time can be reset with manual reset. If total operation time is wanted to be observed on the screen, manual reset is not applied and after Start/Stop operation counting is started from the last count value.

EXAMPLE-2:

There is a production band as shown below. There are two sensors, first is on Ch-A input used for starting the system, second is on Ch-B input used for stopping the system. If

<u>Pro-02</u>=000002; <u>Pro-04</u>=000050; <u>Pro-05</u>=00000 1;



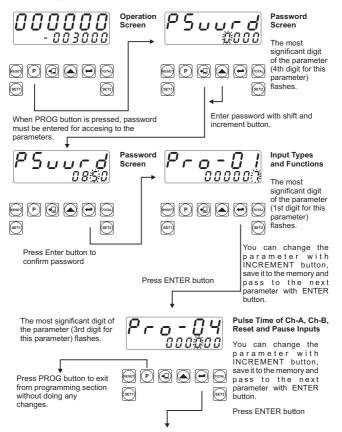
When the object passes in front of the first sensor on Ch-A input, counting is started (Minute / second).

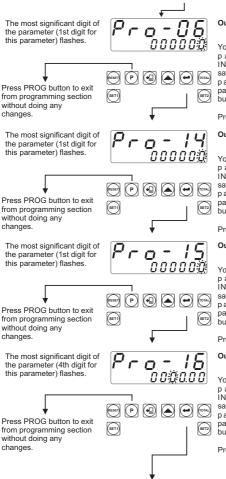
When the object passes in front of the second sensor on Ch-B input, counting is stopped.

Time between two objects can be determined.

7.10 Accessing to the Program Parameters

Parameters are grouped as program parameters. Accessing to the program parameters is same for all functions. So, only accessing to the program parameters for COUNTER / "TOTALIZER COUNTER" is explained in this section. For details on parameters refer to PROGRAM PARAMETERS section.





Output Functions

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

Output-1 Operation Form

You can change the parameter with NCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

Output-2 Operation Form

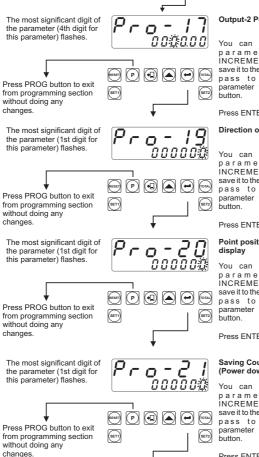
You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

Output-1 Pulse Time

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button



You can change the parameter with INCREMENT button. save it to the memory and pass to the next parameter with ENTER

Press ENTER button

Direction of the Counting

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER

Press ENTER button

Point position for the

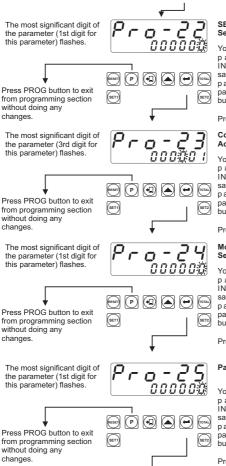
You can change the parameter with INCREMENT button. save it to the memory and pass to the next parameter with ENTER

Press ENTER button

Saving Count Value (Power down back-up)

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER

Press ENTER button



SET1 Operation Form Selection

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

Communication Accessing Address

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

Modbus Protocol Type Selection

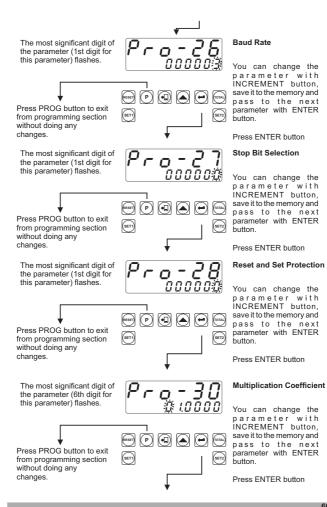
You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

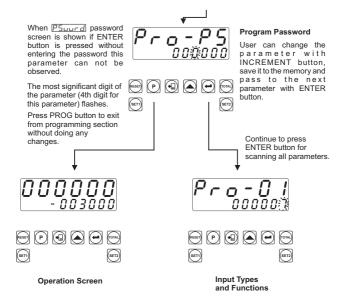
Press ENTER button

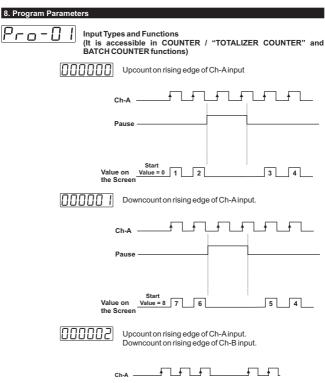
Parity Selection

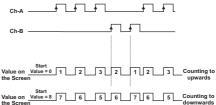
You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

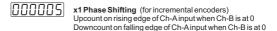




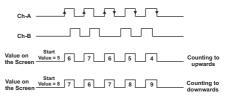




Upcount on rising edge of Ch-Ainput Upcount on rising edge of Ch-B input Value on Value = 0 1 2 3 4 5 6 7 the Screen Value on Value = 8 7 6 Counting to the Screen ПОООООЧ Upcount on rising edge of Ch-Ainput when Ch-B is at 0 Downcount on rising edge of Ch-Awhen Ch-B is at 1 UP DOWN UP Start Value on Value = 0 1 2 \Box Counting to the Screen upwards Value on Value = 8 7 6 Counting to 7



the Screen





downwards



Downcount on rising edge of Ch-Awhen Ch-B is at 1

Upcount on falling edge of Ch-Awhen Ch-B is at 1



Value = 8 7 6 5 4 3 4 5 6 7

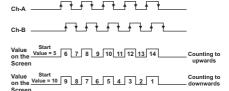
If Pro-01 is 000006, Pro-04 must be 000000 .If not counting is not performed.

[nnnnn]

the Screen

x4 Phase Shifting (for incremental encoders) Upcount on rising edge of Ch-A when Ch-B is at 0 Downcount on falling edge of Ch-A when Ch-B is at 0 Downcount on rising edge of Ch-A when Ch-B is at 1 Upcount on falling edge of Ch-A when Ch-Bis at 1

Downcount on rising edge of Ch-B when Ch-A is at 0 Upcount on falling edge of Ch-B when Ch-A is at 0 Upcount on rising edge of Ch-B when Ch-A is at 1 Downcount on falling edge of Ch-B when Ch-A is at 1





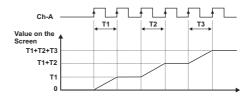
If Pro-01 is 000007, Pro-04 must be 000000. If not counting is not performed.



Selection of Input Type Function for Chronometer (It is accessible only in CHRONOMETER function)

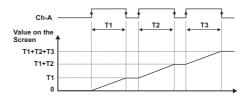
000000

Period measurement in Ch-Ainput.



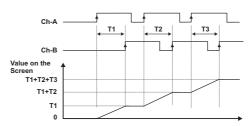
00000 1

Pulse time measurement in Ch-Ainput.



000002

Sum of the time difference between Ch-A and Ch-B inputs rising edges



(i)

Input type function selection parameter $\boxed{P - o - D}$ for chronometer is performed according to the time range is set in Time Unit and Scale selection parameter $\boxed{P - o - D}$

	of Measuring Method essible only in FREQUENCYMETER / TACHOMETER
Function)	
000000	Frequency or cycle is calculated by measuring cycle time of the signals in Ch-Ainput
00000 1	Frequency or cycle is calculated by counting the pulses in Ch-A input during the time is set in measurement period parameter $\boxed{P_{PO} - 0}$
Frequencymeter/Tach	e methods, refer to Section 7.8.1"Examples About ometerFunctionApplications" ms in Frequencymeter / Tachometer function.
	e of Ch-A, Ch-B, Reset and Pause Input sible in functions except for TIMER function)
is less than the c It can be adjuste []][][][][]then t	ect against the electrical contact debounce or the signal that letermined pulse time. If from [00000] to [000050] msec . If it's adjusted to there is no time protection for Ch-A and Ch-B. If the parameter di [000000] or [000000] then Reset and Pause protection ted as 2 msec.
	ctions parameter Pro-01 is 000005, 000005 or me of Ch-A and Ch-B parameter Pro-04 must be ing is not performed.
	of Time Unit and Scale sible in TIMER and CHRONOMETER functions)
000000	Hour/Minute It can be adjusted from [[]] to [[]] 9959
00000 1	Minute / Second It can be adjusted from []]]]]]] to []]]959
000002	Second / Millisecond It can be adjusted from [000000] to [009999]
000003	Hour/Minute It can be adjusted from [[[[]]]] to [[[]]] 2359



After adjustment of Time Range parameter Propis , if SET1 and SET2 values are not appropriate for this selection, SET1 and SET2 are changed according to this selection. (E.g. If time range is 99.99 and SET1 is 45.94, there is no problem. If time range is 99.59 and SET1 is 45.94, then SET1 is changed as 45.59)

Pro-05

Output Functions

(It is accessible in functions except for FREQUENCYMETER / TACHOMETER function)

It can be adjusted from \$\int\text{\Omega} \alpha \int\text{\Omega} \al

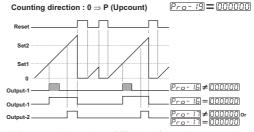
This parameter can be adjusted from @@@@@loto@@@@lin Batch Counter function and operates different from the other functions.

Pro-06⇒000000

Manual Reset-1.

Device continues to count till manual reset is applied. Output-2 pulse time $P_{\Gamma, G}$ - |T| is not considered.

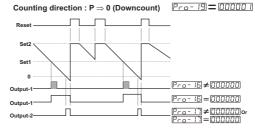
How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:



When count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time $\boxed{Pr_O - I_D}$ is $\boxed{00000000}$, Output-1 does not change condition until manual reset input is active. If Output-1 pulse time $\boxed{Pr_O - I_D}$ Is not 0, at the end of the pulse time Output-1 becomes inactive. When count value reaches to SET2 value, Output-2 becomes active. Counting continues over SET2 value. Output-2 pulse time $\boxed{Pr_O - I_D}$ Is not considered.

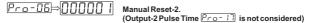
Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

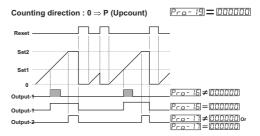


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 Pulse Time $\begin{array}{ccc} P_{CO} & I_D \\ \hline \end{array}$ is $\begin{array}{ccc} \hline D & D \\ \hline D & D \\ \hline \end{array}$, output-1 does not change condition until manual reset input is active. If Output-1 pulse time $\begin{array}{ccc} P_{CO} & I_D \\ \hline D & D \\ \hline \end{array}$ is not 0, Output-1 becomes inactive at the end of the pulse time. When actual value reaches to $\begin{array}{ccc} \hline D & D & D \\ \hline D & D & D \\ \hline \end{array}$, Output-2 becomes active. Counting countinues under $\begin{array}{ccc} \hline D & D & D \\ \hline D & D & D \\ \hline \end{array}$ output-2 pulse time $\begin{array}{ccc} \hline P_{CO} & -1 \\ \hline \end{array}$ in not considered.

Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.



How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:



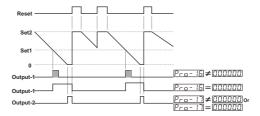
When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time Pro-1b is $\boxed{1000000}$, Output-1 does not change position until manual reset input is active. If Output-1 pulse time $\boxed{Pro-1b}$ is not 0, Output-1 becomes inactive at the end of the pulse time.

When the count value reaches to SET2 value, Output-2 becomes active. Counting does not continue over SET2 value. For starting to count manual reset input must be active. Output-2 Pulse Time Pro-1 Is not considered.

Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

Counting direction : P ⇒ 0 (Downcount) Pro- 19 = 00000 1



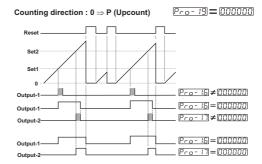
When the count value reaches to \$\text{DDDDD} value, Output-2 becomes active. Counting does not continue under \text{DDDDD} . For starting to count manual reset input must be active. Output-2 pulse time \text{Pro-17} ls.not considered

Count value is added to total count value when manual reset is active in COUNTER/ "TOTALIZER COUNTER" functions.



Manual Reset-3.
Counting continues until Manual Reset input is active.
(Output-2 Pulse Time Pro-17 is considered)

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

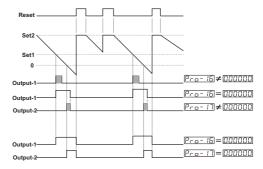


When the count value reaches to SET2 value, Output-2 becomes active. Counting continues until manual reset input is active. If Output-2 Pulse Time $\boxed{P_{CO} - \Gamma}$ is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:





When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time $P_{-D} - I_{\overline{D}}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $P_{-D} - I_{\overline{D}}$ is 000000 it changes position until Manual Reset input is active or according to Output-2.

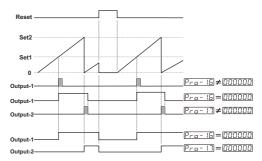
When count value reaches to $\boxed{0000000}$ value, Output-2 becomes active. Counting continues until manual reset input is active. If Output-2 Pulse time $\boxed{\begin{subarray}{c} $ P_{CO} - 1 \end{subarray}}$ is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.



How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:





When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time $\frac{|P_{-Q} - I_0|}{|P_{-Q} - I_0|}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\frac{|P_{-Q} - I_0|}{|P_{-Q} - I_0|}$ is $\frac{|Q_0 - I_0|}{|Q_0 - I_0|}$, it changes position until Manual Reset input is active or according to Output-2 position.

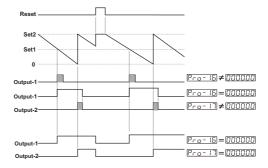
When the count value reaches to SET2 value, Output-2 becomes active. Count value is reset. If Output-2 pulse time $\boxed{P_{-D} - 1}$ is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active. It becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.



How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:

Counting Direction : $P \Rightarrow 0$ (Downcount) P = 000000



When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time $\lceil \frac{r_0 - r_0}{r_0} \rceil$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\lceil \frac{r_0 - r_0}{r_0} \rceil$ is changes position until Manual Reset input is active or according to Output-2 position.

When the count value reaches to TOTOTO value, Output-2 becomes active. Count value becomes equal to Set-2 value and counting is started again. If Output-2 pulse time Pro-II is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

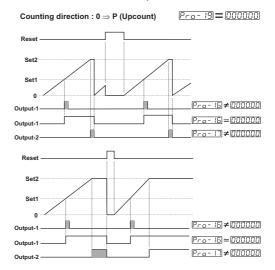


If output functions parameter [은 p - 15] is selected Automatic Reset ([10000] ([100





How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:



When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time $\boxed{P_{ra} - \overline{ls}}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\boxed{P_{ra} - \overline{ls}}$ is $\boxed{0.000000}$, it changes position until Manual Reset input is active or according to Output-2 position.

When the count value reaches to SET2, Output-2 becomes active. Counting is stopped. If Output-2 pulse time $\boxed{ Pro-1 }$ is not 0, count value is reset and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

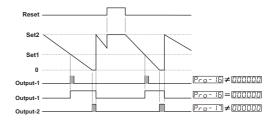
Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

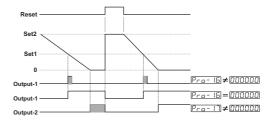


| foutput functions parameter | Pro - 15 | is selected Automatic Reset (| 100003 | 1000005 | 1000005 | then | Pro - 17 | must be different from zero. If not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:

Counting direction: $P \Rightarrow 0$ (Downcount) P = 0.0000 J



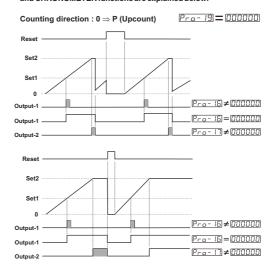


When the count value reaches to TITTE value, Output-2 becomes active. Counting is stopped. If Output-2 pulse time Pro-IT is not 0, count value becomes equal to SET2 value, counting is started again and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER/"TOTALIZER COUNTER" functions.

(i)

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:



When the count value reaches to SET1, Output-1 becomes active If Output-1 pulse time $\boxed{P_{-D} - I_D}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\boxed{P_{-D} - I_D}$ is $\boxed{0.00000}$, it changes position until Manual Reset input is active or according to Output-2 ossition.

When the count value reaches to SET2, Output-2 becomes active and count value is reset.

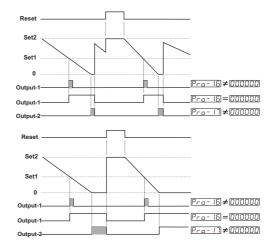
When the count value reaches to SET2, Output-2 becomes active and count value is reset. But SET2 value is observed in actual value display. If Output-2 pulse time $\frac{\mathbb{P} \cdot \mathbb{P}^{-1}}{\mathbb{P}^{-1}}$ is not 0, count value is observed in actual value display and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.



How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functiona are explained below:





When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time $\boxed{P_{CO} - 16}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\boxed{P_{CO} - 16}$ is $\boxed{0.000000}$, it changes position until Manual Reset input is active or according to Output-2 position.

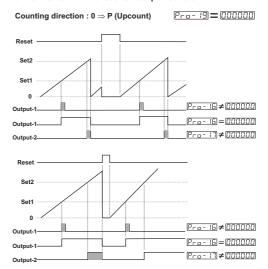
When the count value reaches to TTTTTT value, Output-2 becomes active, count value becomes equal to SET2and counting continues. But TTTTTT value, but the street in the st

Count value is added to total count value when automatic reset is active in COUNTER /" TOTALIZER COUNTER" functions.





How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:



When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time $\boxed{P_{ro} - 15}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\boxed{P_{ro} - 15}$ is $\boxed{000000}$, it changes position until Manual Reset input is active or according to Output-2 position.

When the count value reaches to SET2, Output-2 becomes active and counting continues over 0. If Output-2 pulse time Pro-! is not 0, count value is reset and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

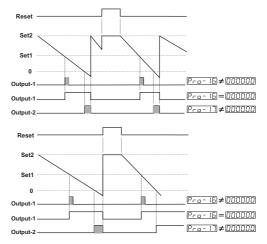
Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

(i)

| foutput functions parameter | P-o - □5 is selected Automatic Reset (□□□□□∃ | □□□□□□□ | □□□□□□ | □□□□□□ | then P-o - □ | must be different from zero. If not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:





When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time $\boxed{P_{CQ} - \boxed{S}}$ is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time $\boxed{P_{CQ} - \boxed{S}}$ is $\boxed{0.00000}$, it changes position until Manual Reset input is active or according to Output-2 position.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

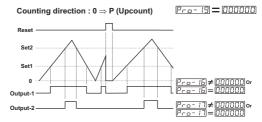




Automatic Reset-5

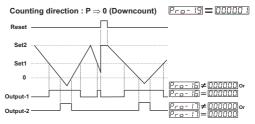
Pulse times $P_{CO} - \frac{1}{16}$ and $P_{CO} - \frac{1}{17}$ is not considered.

How it operates in COUNTER / "TOTALIZER COUNTER" functions are explained below:



If count value is equal or greater than SET1 value, then Output-1 becomes active. Output-1 pulse time $P_{-Q} - \frac{1}{15}$ is not considered. If count value is equal or greater than SET2 value, then Output-2 becomes active. If count value is less than SET2 value, Output-2 becomes inactive. Output-2 pulse time $P_{-Q} - \frac{1}{15}$ is not considered.

Count value is added to total count value when Manual Reset is performed.



If count value is equal or less than SET1 value, then Output-1 becomes active. If it is greater than SET1 value, Output-1 becomes inactive. Output-1 pulse time $\boxed{P_{\Gamma O} - I_{O}^{2}}$ is not considered.

If count value is equal or less than \(\) value, then Output-2 becomes active. If count value is greater than \(\) value, then Output-2 becomes inactive. Output-2 pulse time \(\bar{\mathbb{P}_{\mathbb{P}_{\mathbb{O}}} - \bar{\mathbb{I}} \) is not considered.

Count value is added to total count value when Manual Reset is performed.



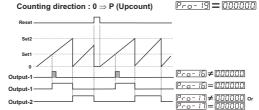
It is preferred if upcount and downcount is performed at the same time.



Automatic Reset-5

Output-2 Pulse Time Pco-! is not considered

How it operates in TIMER and CHRONOMETER functions are explained below:

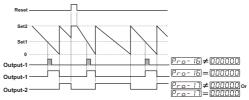


If count value is equal to or greater than SET1 value, then Output-1 becomes active. If Output-1 pulse time Pro- 15 is not 0, Output-1 changes position at the end of the pulse time. If Output-1 pulse time Pro-15 Is 000000, then Output-1 becomes inactive when count value reaches to SET2 value.

When count value reaches to SET2 value, count value is reset and Output-2 becomes active. Output-2 does not change position until count value reaches to SET2 value again.

Output-2 pulse time Pro- 17 is not considered.

Pro-19 = 000001Counting direction : P ⇒ 0 (Downcount)



If count value is equal to or less than SET1 value, then Output-1 becomes active. If Output-1 pulse time Pro- 15 is not 0, Output-1 changes position at theend of the pulse time. If Output-1 pulse time Pro-15 Is 000000, when count value reaches to 000000

Output-1 becomes inactive.

When count value reaches to 000000, count value becomes equal to SET2 value and Output-2 becomes active. Output-2 does not change position until count value reaches to [][][][][] again. Output-2 pulse time Pro- 17 Is not considered.

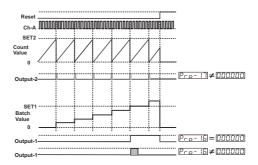


Pro-06⇒NNNNN

How it operates in BATCH COUNTER function is explained below:

Counting direction : 0 ⇒ P (Counting to upwards)

Manual Reset

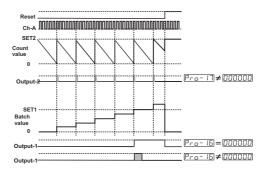


When count value reaches to SET2 value, count value is reset and Output-2 becomes active. If Output-2 pulse time $\boxed{ \boxed{ \begin{tabular}{c} \begin$

When Output-2 becomes active, batch count value is added 1(Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET-1 value, then Output-1 becomes active. If Output-1 pulse time $P_{\Gamma O} = I_{O}$ is $P_{O} = I_{O}$ is input is active. If Output-1 pulse time $P_{O} = I_{O}$ is not, then Output-1 pulse time $P_{O} = I_{O}$ is not, then Output-1 becomes inactive at the end of the pulse time.

How it operates in BATCH COUNTER function is explained below:





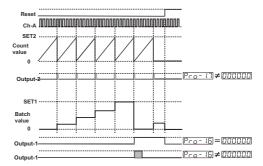
When count value reaches to $\boxed{000000}$, count value becomes equal to SET2 and Output-2 becomes active. If Output-2 Pulse Time $\boxed{r_o-1}$ is $\boxed{000000}$, then Output-2 does not change position until manual reset input is active. If Output-2 pulse time $\boxed{r_o-1}$ is not 0, then Output-2 becomes input is active. If Output-2 pulse time.



Automatic Reset

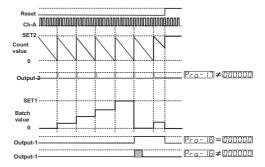
How it operates in BATCH COUNTER function is explained below:





When count value reaches to SET2 value, count value is reset and Output-2 becomes active. If Output-2 pulse time $\boxed{P_{-D} - 1}$ is $\boxed{0000000}$ Then Output-2 does not change position until manual reset input is active. If Output-2 pulse time $\boxed{P_{-D} - 1}$ is not 0, Output-2 becomes inactive at the end of the pulse time.

When Output-2 becomes active, 1 is added to batch count value is (Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET1 value, then Output-1 becomes active and Batch count value is reset automatically. If Output-1 pulse time $\boxed{Pro-1E}$ is $\boxed{D00000}$, then Output-1 does not change position until manual reset input is active. If Output-1 pulse time $\boxed{Pro-1E}$ is not 0, then Output-1 becomes inactive at the end of the pulse time.



When count value reaches to $\boxed{0.0000}$ value, count value becomes equal to SET2 value and Output-2 becomes active. If Output-2 pulse time $\boxed{P_{CO} - 1}$ is $\boxed{0.0000}$, then Output-2 does not change position until manual reset input is active. If Output-2 pulse time $\boxed{P_{CO} - 1}$ is not 0, Output-2 becomes inactive at the end of the pulse time.

When Output-2 becomes active, 1 is added to batch count value is (Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET1 value, then Output-1 becomes active and Batch count value is reset automatically. If Output-1 pulse time Pro-15 is DIDDED, then Output-1 does not change position until manual reset input is active. If Output-1 pulse time Pro-15 is not 0, then Output-1 becomes inactive at the end of the pulse time.



Time Out (Input Signal Reset Time)

(It is accessible only in FREQUENCYMETER / TACHOMETER function)

Actual count value is reset if no signal is applied to Ch-A input for a time which is greater than the value is set in this parameter. It can be adjusted from [00000] It to [000099]



This parameter is visible if Pro-1 measurement method selection parameter is 000000 . Only Ch-A input is performed in Frequencymeter/Tachometer



Measurement Period

(It is accessible only in FREQUENCYMETER / TACHOMETER Function)



This parameter is visible if Pro 3 measurement method selection parameter is 0000 n. Only Ch-A input is performed in Frequencymeter/Tachometer functions



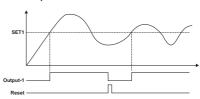
Output-1 Function

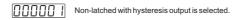
(It is accessible only in FREQUENCYMETER / TACHOMETER Function)



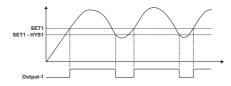
Output is latched. Output-1 does not change position until Manual reset is applied.

Output-1 is latched





Output-1 is non-latched



Output-1 is an alarm output. For details, refer to Alarm Functions for Output-1 parameter Pro-1

Only Ch-A input is performed in Frequencymeter/Tachometer functions

<u> Pro- 10</u>

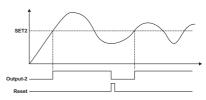
Output-2 Function

(It is accessible only in FREQUENCYMETER / TACHOMETER Function)

000000

Output is latched. Output-2 does not change position until Manual reset is applied.

Output-2 is latched



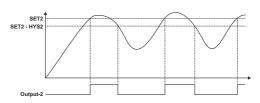
(i)

Only Ch-A input performs in Frequency meter / Tachometer function.

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Non-latched with hysteresis output is selected.

Output-2 is non-latched



Only Ch-A input is performed in Frequencymeter/Tachometer functions

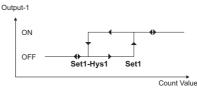
Pro- ! !

Alarm Functions for Output-1

(It is accessible only in FREQUENCYMETER / TACHOMETER Function)

If Output-1 function parameter P_{co} is selected Q_{co} Alarm output, then Output-1 becomes active according to this parameter.

High Alarm.



Low Alarm.

Output-1

ON

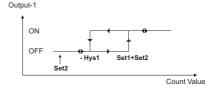
OFF

Set1 Set1+Hys1

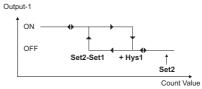
Count Value

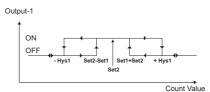
Only Ch-A input performs in Frequencymeter / Tachometer function.

Deviation High Alarm.



Deviation Low Alarm.





Only Ch-A input performs in Frequencymeter / Tachometer function.



It defines hysteresis for Output-1. It is used if Output-1 is non-latched. It can be adjusted from $\fbox{1}\$ to $\fbox{1}\$

Only Ch-A input performs in Frequencymeter / Tachometer function.

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Direction of Counting (It is accessible in functions except for FREQUENCYMETER/TACHOMETER functions)							
000000	Upcount. ($0 \Rightarrow Preset$)						
00000	Downcount. (Preset \Rightarrow 0)						
If Input Types and Functions parameter Pro-0 is [00000] or [00000] in COUNTER / "TOTALIZER COUNTER" functions, then direction of counting parameter Pro-19 can not be accessed.							
Point Position for Display (It is accessible in functions except for TIMER and CHRONOMETER functions)							
000000	No point	000000					
00000 1	Between first and second digits	000000					
000002	Between second and third digits	000000					
000003	Between third and fourth digits	000000					
000004	Between fourth and fifth digits	00.0000					
Saving Count Value (Power down back-up) (It is accessible in functions except for FREQUENCYMETER/TACHOMETER functions)							
Count value is saved to memory when power is disconnected and restored on power up.							
00000 1	Count value is not saved to disconnected. When power up						

screen.

	ration Form Selection essible only in COUNTER / "TOTALIZER COUNTER"
000000	Absolute operation.SET1 can be adjusted from 000000 to 99998
00000	Operation with offset. SET1 can be defined \pm Offset according to SET2 value.(SET1 = SET1 + SET2)
	For example ;if operation with offset is selected, SET1 = 5000, SET2 = 10000. Output-1 becomes active or inactive according to SET1 = 5000 + 10000 = 15000 value
	For example; If operation with offset is selected; If 6th digit of the SET1 is adjusted to "-", SET1 becomes negative (For details, refer to Section 7.3) SET1 = -05000; SET2 = 10000 Output-1 becomes active or inactive according to SET1 = -5000 +10000 = 5000 value
	Iress dress for serial communication bus. djusted from [[[]] to [[]] [[]] 기
Pro-24 Modbus F	Protocol Type Selection
000000	Modbus ASCII protocol is selected
00000 1	Modbus RTU protocol is selected
P-0-25 Communi	cation Parity Selection
000000	No parity
00000 1	Odd Parity
000002	Even Parity

P 25 Baud Rate						
000000	1200 Baud Rate					
00000 1	2400 Baud Rate					
000002	4800 Baud Rate					
000003	9600 Baud Rate					
000004	19200 Baud Rate					
P Communication Stop Bit selection						
000000	1 Stop Bit					
00000 1	2 Stop Bits					
P P _ Reset and Set protection (For accessing from front panle)						
000000	There is no Reset and Set protection					
00000 1	Only RESET button protection is active. Actual value can not be reset by Reset button. Actual value can be reset only reset input is active					
000002	SET1 and SET2 can not be changed.					
000003	Full protection; Reset protection is active, also SET1 and SET2 can not be changed.					
000004	SET1 can not be changed.					
000005	SET2 can not be changed.					
P Frequency / Cycle Coefficient						

Frequency/Cycle Coefficient (It is accessible only in FREQUENCYMETER / TACHOMETER

functions)
It can be adjusted from [10000 1] to [109999]. Count value is multiplied

with this parameter.

If it is [[]]] multiplication is not performed. So number of pulses are displayed without having any changes.

Pr	o	_	3	Mul

Multiplication Coefficient (It is accessible except for TIMER and CHRONOMETER functions)

It can be adjusted from [] [] to [] 99999 . Changes in this parameter is evaluated when counting starts.

If it is [] [] multiplication is not performed. So number of pulses are displayed without having any changes.



Program Password

If it is (1000000), there is no password protection while accessing to the parameters.

When programming button is pressed, ProL will appear on the display.

If program password is not "0" while accessing to the program parameters;

1- If user does not enter the PSuurd value correctly; operation screen will appear without entering to operator parameters.

2-When PSuurd in top display and DDDDD in bottom display,if user presses ENTER button without entering password (for observing the parameters):

User can see all parameters except Program Password but device does not allow to do any changes with parameters.

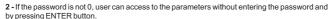
(Please refer to Section 9. Failure Messages in EZM-9950 Programmable Timer & Counter (2))

9. Failure Messages in EZM-9950 Programmable Timer & Counter

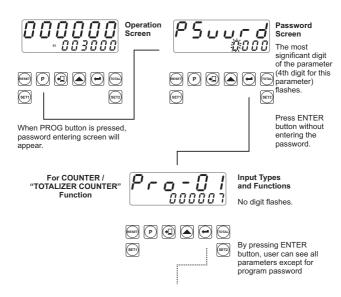


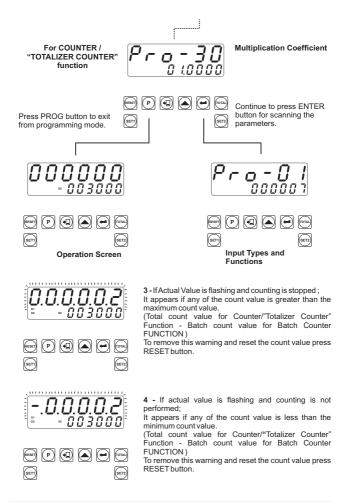
1 - Position of the DIP Switch is wrong. (DIP Switch determines the operation function of the device and it is under the top cover)

For details, refer to Section 2.8 "Selection of Operation Function and Input Type with DIP Switch".



User can see all parameters except for programming password parameter [Pro-P5] but user can not do any changes in parameters. If password is entered for accessing to the parameters correctly, most significant digit of the parameter flashes. But if the password is not entered, flashing of the most significant digit is not realised.





10. Specifications

Device Type : Programmable Timer & Counter

Housing & Mounting : 96mm x 96mm x 87.5mm 1/4 DIN 43700 plastic housing

for panel mounting. Panel cut-out is 92x92mm

Protection Class : NEMA 4X (IP65 at front, IP20 at rear).

Weight : Approximately 0.34 Kg.

Environmental Ratings : Standard, indoor at an altitude of less than 2000 meters

with none condensing humidity Storage / Operating Temperature: -40 °C to +85 °C / 0 °C to +50 °C Storage / Operating Humidity : 90 % max. (None condensing)

Installation · Fixed installation

Over Voltage Category

Pollution Degree : II. office or workplace, none conductive pollution

Operating Conditions : Continuous

Supply Voltage and Power : 100 - 240 V~ 50/60 Hz. (-15% / +10%) 6VA

24 V~ 50/60 Hz. (-15% / +10%) 6VA

24 V=== (-15% / +10%) 6W

Electrical Characteristics Of Digital Inputs

: Rated voltage : 16 VDC @ 5mA

Maximum continuous permissible voltage: 30 VDC

Logic 1 minimum level: 3 VDC Logic 0 maximum level: 2 VDC

Maximum Input Frequency : For Counter / "Totalizer Counter" and Batch Counter;

If $P_{CQ} = 0$; | = 0, 1, 2; 6000Hz If $P_{-0} - 0 = 3, 4;4000Hz$ If $P_{CO} = \Pi I = 5.6 : 3500 Hz$ If $P_{CQ} - Q | 1 = 7 ; 2000 Hz$

For Frequencymeter / Tachometer: 10kHz Max 30 Hz (Prn-ПЧ ≠ ПППППП, debounce)

:-EMO-900 Relay Output Module (5A@250V~) **Optional Output Modules**

> 100.000 operation (Full Load) -EMO-910 SSR Driver Output Module(Max20mA@18V---)

-EMO-920 Digital (Transistor) Output Module

: EMC-900 RS-232 Communication Module

: EMC-910 RS-485 Communication Module

: MODBUS-RTU, MODBUS-ASCII

: 14 mm Red 6 digit LED display

: 9 mm Green 6 digit LED display

(Max 40mA@18V===)

Standard Communication Module

Optional Communication

Module

Communication Protocol

Process Display Set Display

: SV1 (Set1 value), SV2 (Set2 value), OP1 / 2 (Control Led Indicators or Alarm Output) LEDs

Approvals

: UL Recognized Component(File Number: E 254103), GOST-R, (€